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Solved Problems in Classical Mechanics

The velocity vector components are: $v_y = dy/dt$, $v_x = dx/dt$ The vector components of the vector that connects the particle to the point on the x-axis are: $V_y = y(t)$, $V_x = x(t) f(t)$ For these to be the same, then $v_y v_x = V_y V_x$ $dy dx = y(t) x(t) f(t) dy$ $dy(t) = dx x(t) f(t)$ This cannot be integrated with $f(t)$ being arbitrary.

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For example, consider a falling body. $F = mg$ gives $mg = ma$, which can be written as $g = \ddot{y}$, where a dot denotes a time derivative. This is a rather simple differential equation, and you can quickly guess that $y(t) = \frac{1}{2}gt^2$ is a solution. Or, more generally with the constants of integration thrown in, $y(t) = y_0 + v_0 t + \frac{1}{2}gt^2$.

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Classical mechanics is a physical theory describing the motion of macroscopic objects, from projectiles to parts of machinery, and astronomical objects, such as spacecraft, planets, stars and galaxies. For objects governed by classical mechanics, if the present state is known, it is possible to predict how it will move in the future and how it has moved in the past. The earliest development of classical mechanics is often referred to as Newtonian mechanics. It consists of the physical concepts e

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In terms of the original coordinates r and θ , the solutions to these are: $r = \frac{L^2}{mk} [1 + A \cos(\omega t + \phi)]$ $\theta = B \cos(\omega t + \theta_0)$ The phase angles, ϕ and θ_0 , and amplitudes A and B are constants of integration and fixed by the initial conditions.

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Here is a simple exercise to get you started: Find the general solution of the firstorder equation $df/dt = f$ for an unknown function $f(t)$. [There are several ways to do this. One is to rewrite the equation as $df/f = dt$ and then integrate both sides.] How many arbitrary constants does the general solution contain?